



Online Anomaly Detection for Optical Networks

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Introduction

The Architecture



Fig. 1: Fairly stable behavior over time of (a) total number of packets in network, but (b) drastic change in distribution of source IP within a particular flow at t = 2016. Data from NYC core router in Abilene backbone network.

- Network anomalies span wide variety of classes/types. Need online and intelligent, anomaly detection method.
- We propose an online, learning algorithm, based on the Kernel Recursive Least-Squares (KRLS) algorithm.
- We test on data from Abilene backbone network, and compare with offline, block-based algorithm based on Principal Component Analysis (PCA) [1].



Fig. 2: Traffic statistics collected (in distributed manner) at edge nodes, every pre-determined measurement interval. Stats sent to central monitoring unit (CMU) which runs online anomaly detection algorithm, raises alarms.

- Collect following packet header information at edge nodes: {src edge node, dst edge node, srcIP, dstIP}
- Flow defined as {src edge node, dst edge node} pair.
- x_t is Flow Vector, defined as vector giving number of packets (or bytes) in each flow, normalized, at time t.



Fig. 3: Simplified depiction of space spanned by 2 sample dictionary elements, D{1} and D{2}. δ is distance metric, v_1 and v_2 are thresholds where $v_1 < v_2$. Anomaly declared when $\delta > v_2$, D expanded when $v_1 < \delta < v_2$.

<u>Objective</u>: Build a dictionary of flow vectors $D = \{\tilde{\mathbf{x}}_j\}_{j=1}^m$, such that mapping onto feature space, $\{\varphi(\tilde{\mathbf{x}}_j)\}_{j=1}^m$, forms an *approximately* linearly independent basis. φ represents mapping from input space to feature space [2].

The Detection Algorithm

•Initialize at t = 1, by entering x₁ into dictionary.

•<u>Iterate</u> for t = 2,3,...

Step 1: New data arrive. Evaluate δ_i , the **degree** of **linear dependence** of $\varphi(\mathbf{x}_i)$ on the dictionary at time *t* [2]:

$$\delta_{i} = \min_{a} \left\| \sum_{j=1}^{m_{i-1}} a_{j} \phi(\tilde{\mathbf{x}}_{j}) - \phi(\mathbf{x}_{i}) \right\|^{2}$$

(1)

Step 2: Compare δ_i with thresholds v_1 and v_2 , where $v_1 < v_2$: - If $\delta_i > v_2$, new input vector is **very** far away, conclude anomaly. Raise **red alarm**, no change to dictionary. - If $v_1 < \delta_i < v_2$, new input vector not sufficiently explained by dictionary. Add \mathbf{x}_1 to dictionary, raise orange alarm. - If $\delta_i < v_1$, new input vector falls within normal subspace. No alarm, no change to dictionary.





network; (b) growth in *D* for various values of v_1 , with $v_2 = 6v_1$.



<u>Fig. 6</u>: Comparing (a) δ_i in proposed algorithm with $\nu_1 = 0.01$ and $\nu_2 = 6\nu_1$, with (b) energy in residual subspace using block-based PCA from [1]. Spikes represent anomalies.



Fig. 7: Example anomaly at t = 538. Not easily seen in (a) timeseries of packets, but (b) obvious by observing inner product of \mathbf{x}_t from each dictionary member.



Fig. 8: Progression in time of inner product of \mathbf{x}_i with (a) a normal dictionary member, and (b) an anomalous flow vector that was admitted to dictionary.

Conclusions and Future Work

- Algorithm is **recursive**, there is **no need to relearn** from scratch when new data arrive.
- Storage requirement and complexity bounded by O(*m*²), i.e. independent of time.
- Performance comparable to accepted offline, block-based PCA method in [1].
- Work in progress includes controlling dictionary by enabling dropping of obsolete or anomalous elements; confirming anomaly in case of orange alarm if relevant x, exhibits continually low inner product value to subsequent input vectors.
- Future work involves letting the data determine the thresholds v₁ and v₂.

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References

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